



# Asteroid Gravity Test System Using a Planar Air Bearing



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## Motivation

The size and makeup of near earth asteroids make spacecraft sample and return missions hazardous. Since at least one of these asteroids (101955) Bennu regularly ejects particles, nanospacecraft could be deployed to capture these objects in flight, eliminating the need for touching down on the asteroid itself.

The proposed airbearing table is radially curved to mimic the low gravity of a centrally located asteroid, permitting evaluation of such a mission's navigation, guidance and docking.

## Conclusion

Capture of erupting particles is a plausible alternative to touchdown on the asteroid surface

Creation of a radially symmetric air bearing can reproduce aspects of the dynamic environment for system test

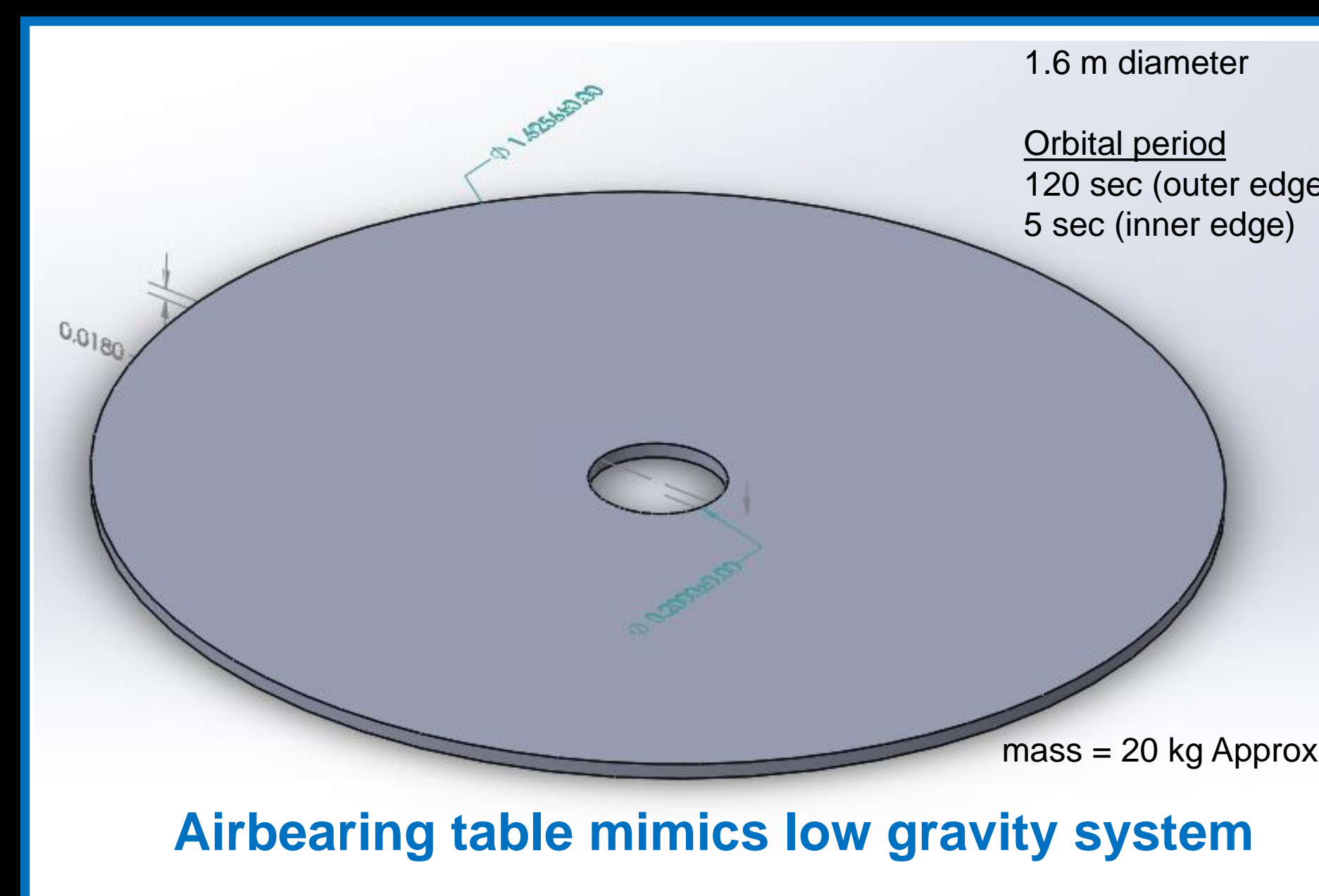
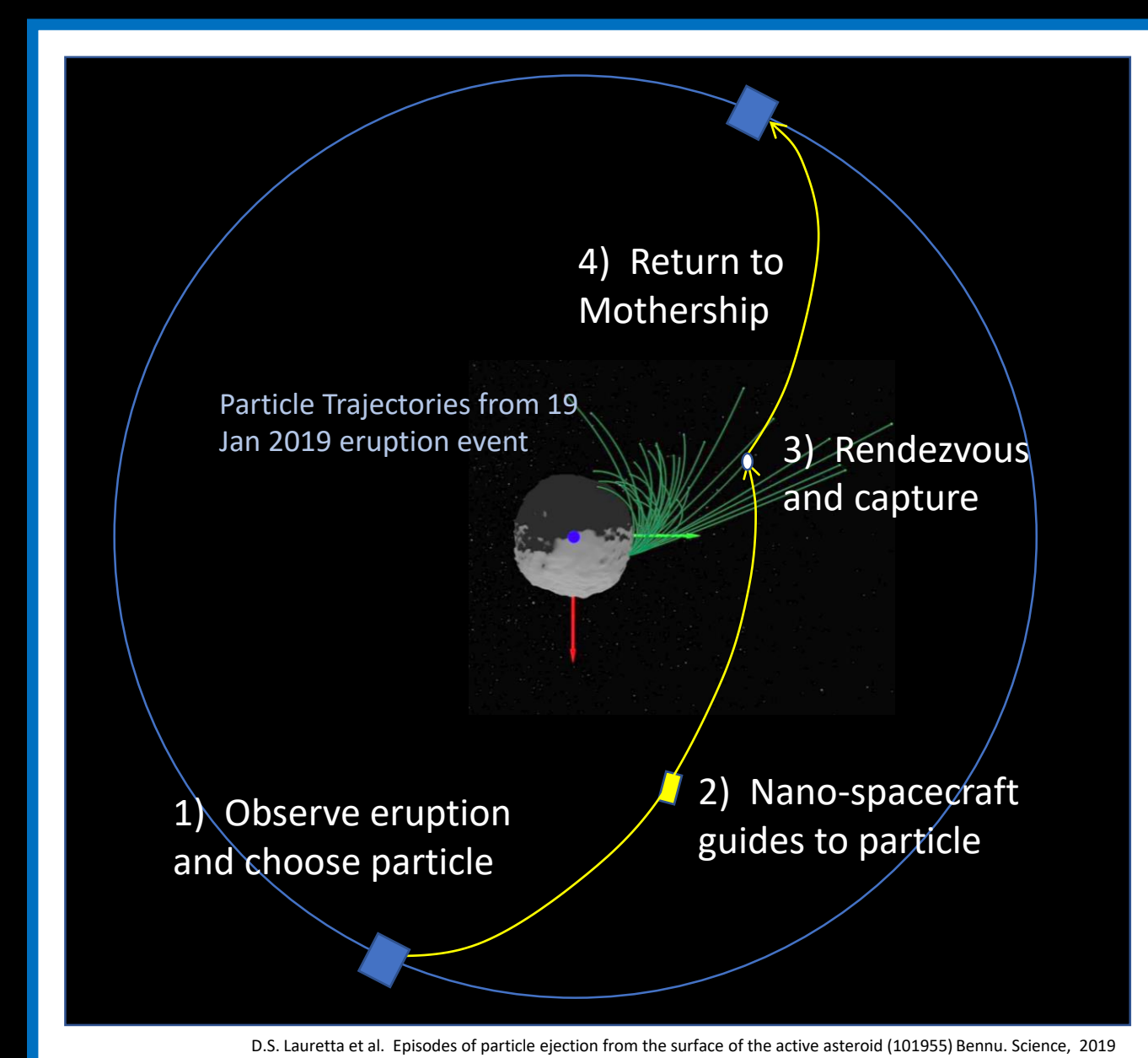
This air bearing table can also be used as a hands on teaching tool for Keplerian dynamics.

## Previous Approach

Planar Airbearing allowing 3 degree of freedom motion

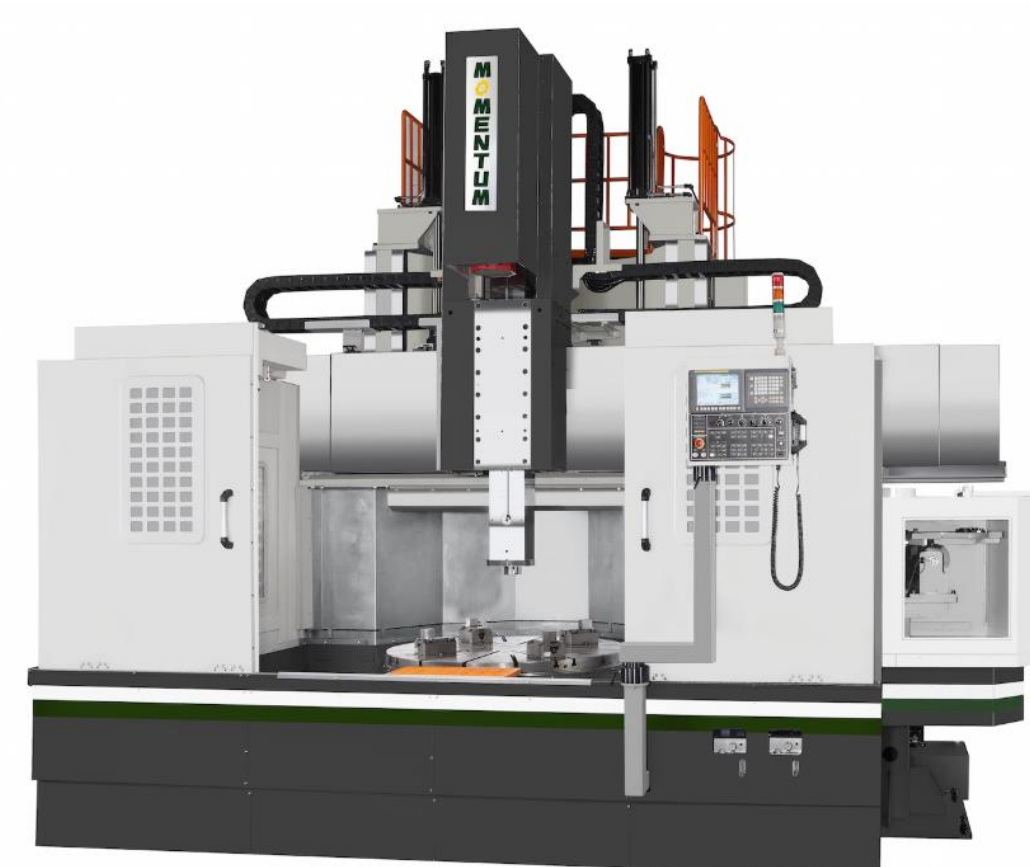
## Updated Approach

Radially sculpted air-bearing table to mimic a low gravity asteroid environment



## Manufacturing

Table requirements well within existing tooling machine capability



		MVL-12	MVL-12M	MVL-12HD
Capacity	Max. Swing Diameter	mm (inch)	631.000 (24.84)	631.000 (24.84)
	Max. Turning Diameter	mm (inch)	631.000 (24.84)	631.000 (24.84)
	Distance From Spindle Turning Head to Table Surface	mm (inch)	0 - 1,200 (0 - 47.24)	0 - 1,195 (0 - 46.29)
	Max. Turning Height	mm (inch)	1,200 (47.24)	1,195 (46.29)
Table	Max. Workpiece Weight	kg (lb)	8,000 (17,637)	8,000 (17,637)
	Table Diameter (Manual Chuck)	mm (inch)	631.250 (24.84)	631.250 (24.84)
	Range of Table Speed (RPM)	rpm	34 - 1,000	26 - 80
	Range of Table Speed (ft/min)	fpm	104 - 312	81 - 312
ATC	Max. of Table Torque	N.m (ft.lbs)	264.12 (193.1)	264.12 (193.1)
	Tool Size	mm (inch)	12 / 25 / 32 / 40 / 50 / 60 / 75 / 85 / 95 / 105 / 120 / 150 / 180 / 200 max. length	12 / 25 / 32 / 40 / 50 / 60 / 75 / 85 / 95 / 105 / 120 / 150 / 180 / 200 max. length
	Tool Type	T - Puller	T - Puller	T - Puller
	Number of Tool Stations	12 (Rotary)	12 (6 Turning + 6 Milling + 1 Chuck)	12 (Rotary)
	Cross Section of Beam	mm (inch)	200 x 200 (7.87 x 7.87)	200 x 240 (7.87 x 9.44)
Travel	Horizontal Travel (Z-Axis)	mm (inch)	630 x 1,000 (24.8 x 39.37)	630 x 1,000 (24.8 x 39.37)
	Vertical Travel (Z-Axis)	mm (inch)	800 (31.5)	1,000 (39.37)
	Cross-Rail Travel	mm (inch)	500 (19.68), 2 stops (3 positions)	500 (19.68), 2 stops (3 positions)
	Rigid Rate (X & Z Axis)	m/min	1.0	1.0
	Cutting Feed Rate	mm/min	1 - 2,000	1 - 2,000
Motor	Feed Override	%	0 - 150	0 - 150
	Main Spindle	kW (HP)	300 (407) / 450 (604) / 600 (811) / 750 (1014) / 900 (1210)	300 (407) / 450 (604) / 600 (811) / 750 (1014) / 900 (1210)
	Feed Servo Motor (X & Z Axis)	kW (HP)	450 (604)	450 (604)
Dimensions	Mill Spindle Motor	kW (HP)	N/A	N/A
	CT Axis Servo Motor	kW (HP)	N/A	N/A
	Floor Space (L x W)	mm (inch)	7,700 x 5,400 (303.1 x 212.6)	6,600 x 6,600 (259.8 x 259.8)
	Machine Max. Height (H)	mm (inch)	5,100 (200.787)	5,700 (224.409)
	Machine Net Weight	kg (lb)	20,000 (44,089)	25,000 (55,098)

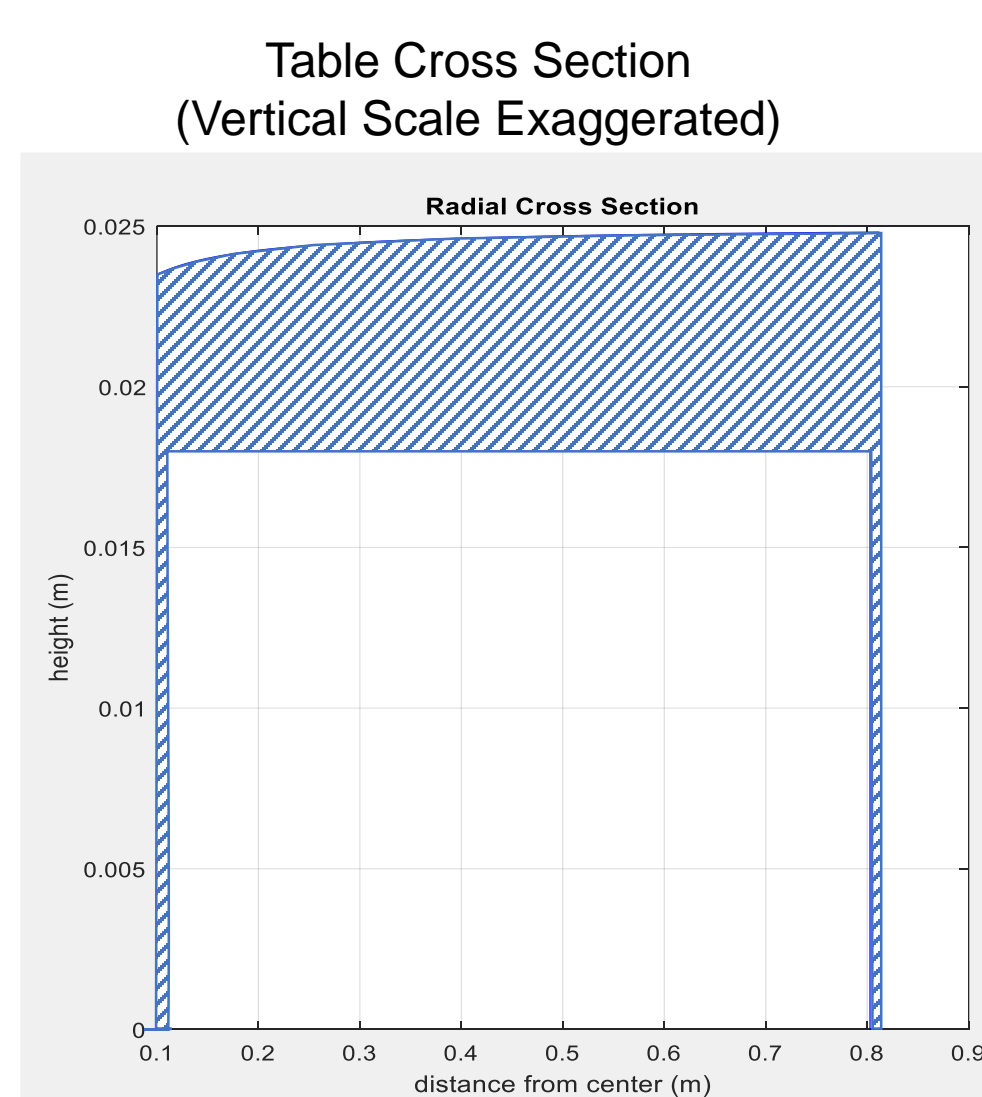
CNC Vertical Turning Lathe Accuracy usually about 0.02mm

## Derivation of Surface

Diameter is chosen consistent with reasonable max handling size ( $r_{max} = 1.6m$ )

Period of max radius orbit limited with ability to level platform ( $t_p = 120$  seconds)

Inner radius limited by ability of air bearings to plausibly maintain lift on a curved surface ( $r_{min} = 0.1m$ )



$$a(r) = -g * slope$$

Inwards acceleration at max radius

$$a(r) = -\frac{k}{r^2}$$

Gravitational model

$$k = -\frac{4\pi^2 r_{max}^3}{t_p^2 g}$$

Value of k for chosen orbital period  $t_p$

$$slope(r) = -\frac{a}{g} = -\frac{-k}{r^2 g}$$

Slope required for that orbital period

$$y(r) = \int slope(r) dr = \int \frac{k}{r^2} dr = -\frac{k}{r} + y_0$$

Integration of slope to get outline

### References

D.S. Lauretta et al. Episodes of particle ejection from the surface of the active asteroid (101955) Bennu. Science, 2019