

Mars Exploratory Balloon (MEB) CubeSats

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Mission Objective

Less than 1% of Mars has been explored. Aerial vehicles provide a method to explore rugged terrain, cliff/canyon walls, RSL, and skylights ¹

Outline

- Overview
- Concept of Operations
- CubeSat System Design
- Altitude Control Model
- Discussion
- Future Goals
- Conclusion

Related Research

Hall, Jeffery, et al. "Flight test results for aerially deployed Mars balloons." *AIAA Balloon Systems Conference*. 2007.

Jones, Jack A. "Inflatable robotics for planetary applications." (2001).

Jones, Jack, and Jiunn Wu. "Solar montgolfiere balloons for Mars." *International Balloon Technology Conference*. 1999.

Farley, Rodger. "Balloon Ascent: 3-D simulation tool for the ascent and float of high-altitude balloons." *AIAA 5th ATIO and16th Lighter-Than-Air Sys Tech. and Balloon Systems Conferences*. 2005.

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Atmospheric Comparison

The atmospheric pressure on Mars is less than 1% of Earth's, resulting in difficult flying conditions for LTA vehicles. However, flight is feasible. 4

Types of Balloons

● Super Pressure Balloon

● Zero Pressure Balloon

● Vacuum Airship

● **Solar Montgolfiere** ⁵

Lift Capacity - Various Gasses

Helium and Hydrogen balloons can lift a 10kg payload at approximately 12m diameter. Solar balloons can lift the same payload at \sim 17m diameter

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Concept of Operations

With a light enough payload, and pre-heating of the envelope, the MEB can achieve buoyancy during EDL. 7

MEB CubeSat System Design

MEB Stowed 12U Configuration MEB Deployed Primary & Vent Gondolas 8

Exploring Mars

MEB collecting science data on an exposed Martian cliff wall: high res-imagery, stratigraphy, core sampling, LIDAR

Anchored MEB, collecting extended atmospheric data and imagery, 1 km above the surface

Envelope Radiation Model $A_{proj} = 0.25 * \pi * d^2$

 $HalfCone_{angle} = \arcsin\left(\frac{R_{Mars}}{R_{Mars} + z}\right)$ Absorbed direct sunlight is denot

$$
Q_{sun} = \alpha * A_{proj} * q_{Sun}
$$

 $ViewFactor = \frac{1 - \cos(HalfCone_{angle})}{2}$

Absorbed Albedo Heat is denoted by:

$$
Q_{Albedo} = \alpha * A_{surf} * q_{Albedo} * ViewFactor
$$

Absorbed Martian Surface IR Heat is denoted by:

$$
Q_{IR,Surface} = \alpha_{IR} * A_{surf} * q_{IR,Surface} * ViewFactor
$$

Emitted IR Energy from the Envelope is denoted by:

$$
Q_{IR,emit} = \sigma * \epsilon * A_{surf} * T_{envelope}^4
$$

The overall heat radiation on the balloon is then denoted by:

$$
Q_{rad} = Q_{sun} + Q_{Albedo} + Q_{IR,Surface} - Q_{IR,emit}
$$
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Energy Balance Equations

Venting for $Q_{vent} = \dot{m} * c_v * (T_i - T_{atm})$ **Altitude Control** Envelope $\frac{dT_s}{dt} = \frac{Q_{rad} + Q_{conv,ext} - Q_{conv,int}}{C_{max} * m}$ **Envelope** $c_{v,env} * m_{envelope}$ $\frac{dT_i}{dt} = \frac{Q_{conv, int} - Q_{vent}}{Q_{vent}}$ **Internal** $dt = c_{v,CO^2} * m_{CO^2}$ **Temperature**

These equations provide the dynamic temperature response as a function of time.

Trajectory for Baseline Balloon Model

A smaller envelope-to-payload ratio results in longer flight times as well as higher maximum achievable altitude.¹²

Altitude Position Control for Baseline Model - With Venting

A smaller vent results in smaller limit cycle, but more vent openings.

As vent size increases, "deadzone" for altitude control increases as well.

Discussion

- Extended sunlight from exploring poles in summer/winter results in longer flights without anchoring
- Mars is a breathing planet, seasonal climate change and winds
- Can compliment other surface vehicles
- **Biggest Challenge**: Multi -day flights

Conclusions

- Flying solar balloons on Mars is challenging but this model shows feasibility of the platform.
- Highly customizable and can be designed for specific missions.
- Future work:
	- 3D control model
	- Terrestrial experiments
	- Swarm and Multi-Agent Systems

Adventure Awaits

