









Mars Exploratory Balloon (MEB) CubeSats

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Mission Objective



Less than 1% of Mars has been explored. Aerial vehicles provide a method to explore rugged terrain, cliff/canyon walls, RSL, and skylights



Outline

- Overview
- Concept of Operations
- CubeSat System Design
- Altitude Control Model
- Discussion
- Future Goals
- Conclusion





Hall, Jeffery, et al. "Flight test results for aerially deployed Mars balloons." *AIAA Balloon Systems Conference*. 2007.

Jones, Jack A. "Inflatable robotics for planetary applications." (2001).

Jones, Jack, and Jiunn Wu. "Solar montgolfiere balloons for Mars." *International Balloon Technology Conference*. 1999.

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Atmospheric Comparison





	MARS	EARTH
Atmospheric Pressure	636 Pa	101325 Pa
Surface Level Temperature	210 K	288.15 K
Air Composition	95% CO2	78% Nitrogen
Distance from Sun	1.524	1 AU
Gravity	3.711 m/s²	9.81 m/s²

The atmospheric pressure on Mars is less than 1% of Earth's, resulting in difficult flying conditions for LTA vehicles. However, flight is feasible.



Types of Balloons

• Super Pressure Balloon

• Zero Pressure Balloon

• Vacuum Airship

• Solar Montgolfiere





Lift Capacity - Various Gasses



Helium and Hydrogen balloons can lift a 10kg payload at approximately 12m diameter. Solar balloons can lift the same payload at ~17m diameter



Concept of Operations





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With a light enough payload, and pre-heating of the envelope, the MEB can achieve buoyancy during EDL.



MEB CubeSat System Design



MEB Stowed 12U Configuration

MEB Deployed Primary & Vent Gondolas



Exploring Mars



MEB collecting science data on an exposed Martian cliff wall: high res-imagery, stratigraphy, core sampling, LIDAR



Anchored MEB, collecting extended atmospheric data and imagery, 1 km above the surface



Envelope Radiation Model $A_{proj} = 0.25 * \pi * d^2$



 $HalfCone_{angle} = \arcsin\left(\frac{R_{Mars}}{R_{Mars} + z}\right)$ Absorbed direct sunlight is denot

$$Q_{sun} = \alpha * A_{proj} * q_{Sun}$$

 $ViewFactor = \frac{1 - \cos\left(HalfCone_{angle}\right)}{2}$

Absorbed Albedo Heat is denoted by:

$$Q_{Albedo} = \alpha * A_{surf} * q_{Albedo} * ViewFactor$$

Absorbed Martian Surface IR Heat is denoted by:

$$Q_{IR,Surface} = \alpha_{IR} * A_{surf} * q_{IR,Surface} * ViewFactor$$

Emitted IR Energy from the Envelope is denoted by:

$$Q_{IR,emit} = \sigma * \epsilon * A_{surf} * T_{envelope}^4$$

The overall heat radiation on the balloon is then denoted by:

$$Q_{rad} = Q_{sun} + Q_{Albedo} + Q_{IR,Surface} - Q_{IR,emit}$$
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Energy Balance Equations

Venting for
Altitude Control $Q_{vent} = \dot{m} * c_v * (T_i - T_{atm})$ Envelope
Temperature $\frac{dT_s}{dt} = \frac{Q_{rad} + Q_{conv,ext} - Q_{conv,int}}{c_{v,env} * m_{envelope}}$ Internal
Temperature $\frac{dT_i}{dt} = \frac{Q_{conv,int} - Q_{vent}}{c_{v,CO^2} * m_{CO^2}}$

These equations provide the dynamic temperature response as a function of time.



Trajectory for Baseline Balloon Model



A smaller envelope-to-payload ratio results in longer flight times as well as higher maximum achievable altitude. 12



Altitude Position Control for Baseline Model -With Venting



A smaller vent results in smaller limit cycle, but more vent openings.

As vent size increases, "deadzone" for altitude control increases as well.



Discussion

- Extended sunlight from exploring poles in summer/winter results in longer flights without anchoring
- Mars is a breathing planet, seasonal climate change and winds
- Can compliment other surface vehicles
- Biggest Challenge: Multi-day flights







Conclusions

- Flying solar balloons on Mars is challenging but this model shows feasibility of the platform.
- Highly customizable and can be designed for specific missions.
- Future work:
 - 3D control model
 - Terrestrial experiments
 - Swarm and Multi-Agent Systems













Adventure Awaits







