

# *Liquid reaction wheel based on MHD effect in liquid Mercury*



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# Short Background



- First Georgian Satellite
  - Already assembled and functioning Ground Station
- Technology demonstration for MHD reaction wheel
- New technology development

# Spherical Air Bearing

- Spherical Air Bearing
  - Roundness  $10 - 20 \mu\text{in}$
  - Surface roughness  $< 16 \mu\text{in}$



# Spherical Air Bearing

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  - Roundness 10 – 20  $\mu in$
  - Surface roughness < 16  $\mu in$

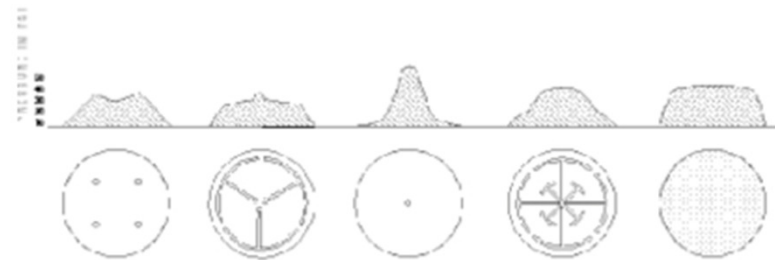


- Bowling Ball Standard Specification
  - Roundness < 0.010"
  - Surface Roughness < 50  $\mu in$



# Spherical Air Bearing

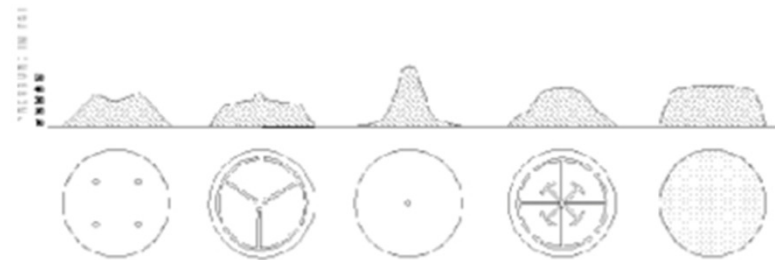
- Roundness
- Surface roughness
- Support
  - # 5) is Good



Pressure (psi) vs Lateral Position of various air bearings; From left to right: 1) Multiple orifices with no grooves, 2) Multiple orifices with distribution grooves, 3) Single orifice, no grooves, 4) Single non restrictive input port with depth and width of grooves providing restriction, 5) Full porous face with 10s of millions of sub-micron pores evenly spaced across the face

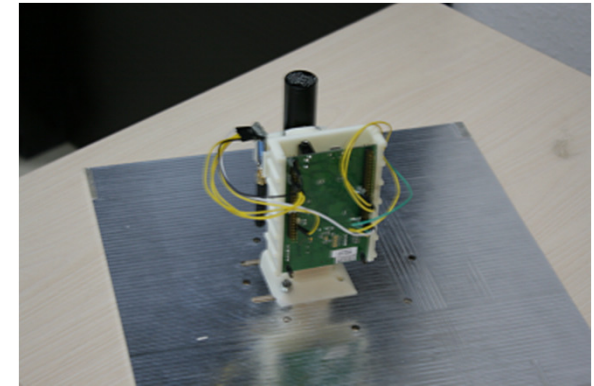
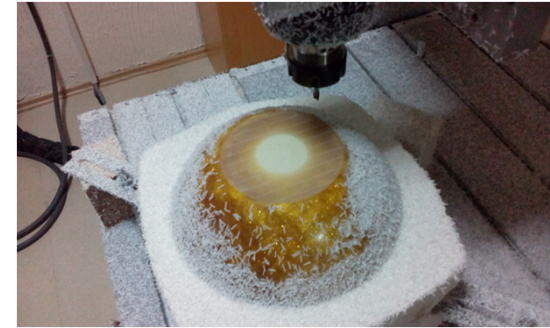
# Spherical Air Bearing

- Roundness
- Surface roughness
- Support
  - # 5) is Good
  - Gypsum is the material to Go!
    - Easy to mold
    - Porous
    - Inexpensive



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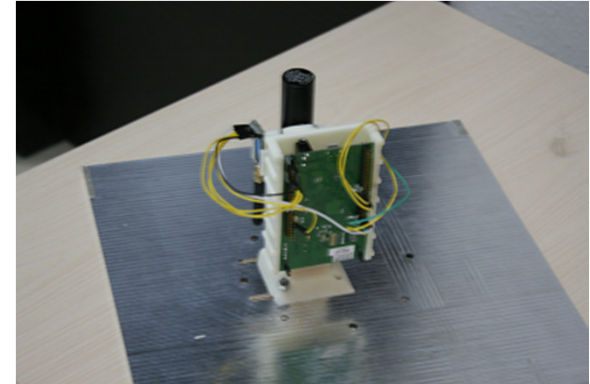
# Spherical Air Bearing





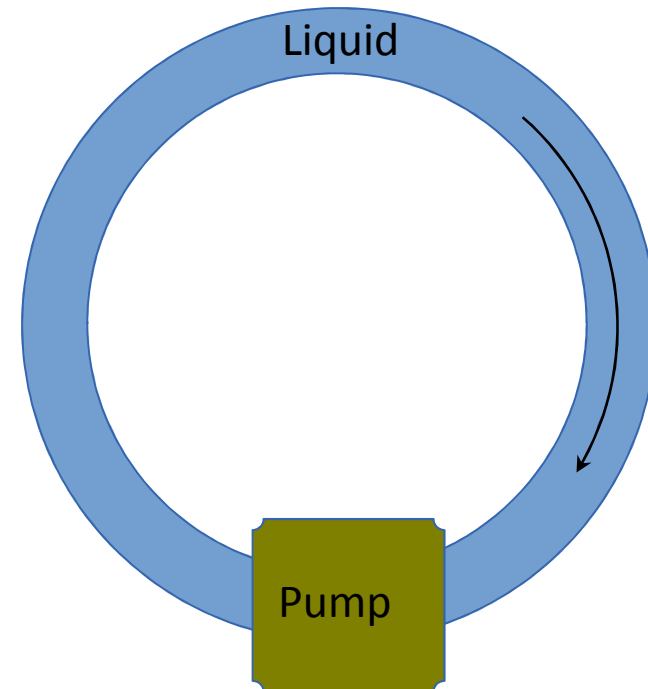
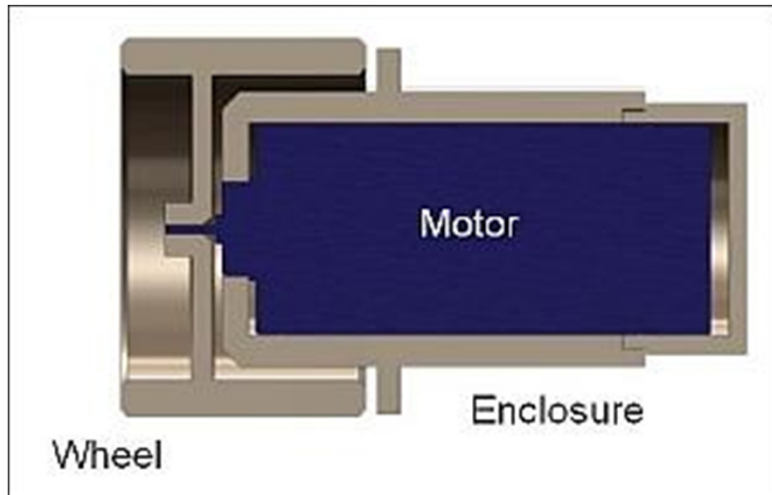
# Kalman + RF

- STM32F407 Discovery Board
  - CC1101 RF board
  - Gyro + B Field + Accelerometer
- 
- STM32F407 computes DCM matrix with implementation of Kalman filter for matrices, and Airds it to the desktop computer which is used for logging, and visualization





# Liquid Reaction Wheel



# Mercury

- Density =  $13.546 \text{ g/cm}^3$ 
  - Lead =  $11.35 \text{ g/cm}^3$
- Melting point =  $-38.8 \text{ }^\circ\text{C}$ 
  - Boiling point =  $356.7 \text{ }^\circ\text{C}$
- Bonus future:
  - Electrical Resistivity =  $961 \text{ n}\Omega \cdot \text{m}$



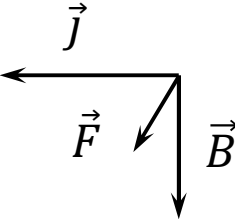
# MHD

Permanent magnet



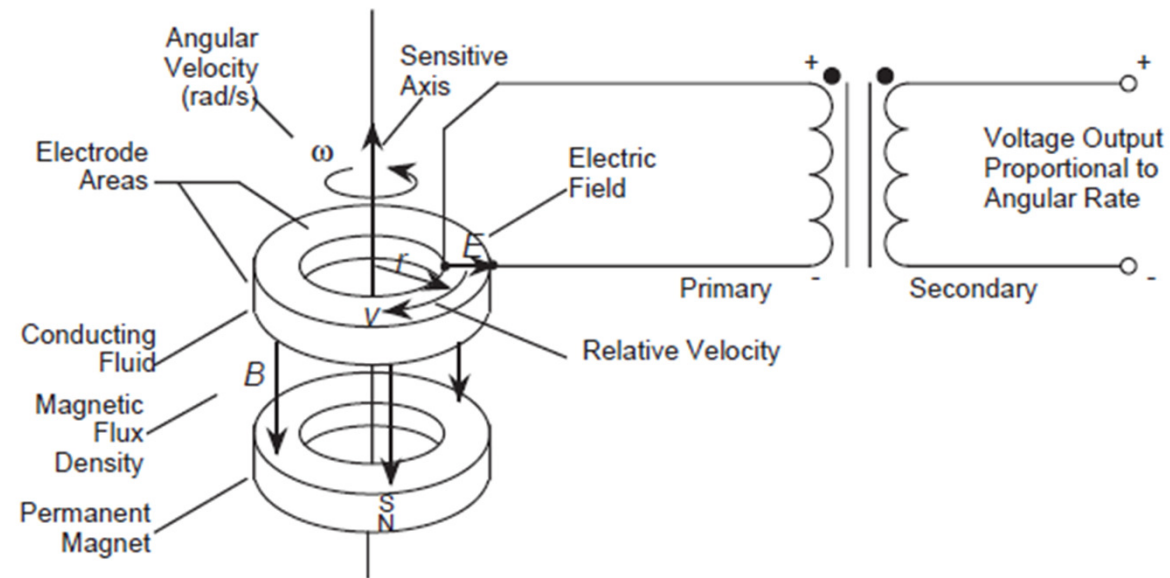
Electrodes

Liquid Mercury



# Other uses

- Angular Displacement Sensor on Advanced Land Observing Satellite (ALOS)



AIAA Guidance, Navigation, and Control Conference  
10 - 13 August 2009, Chicago, Illinois

# Pros and Cons

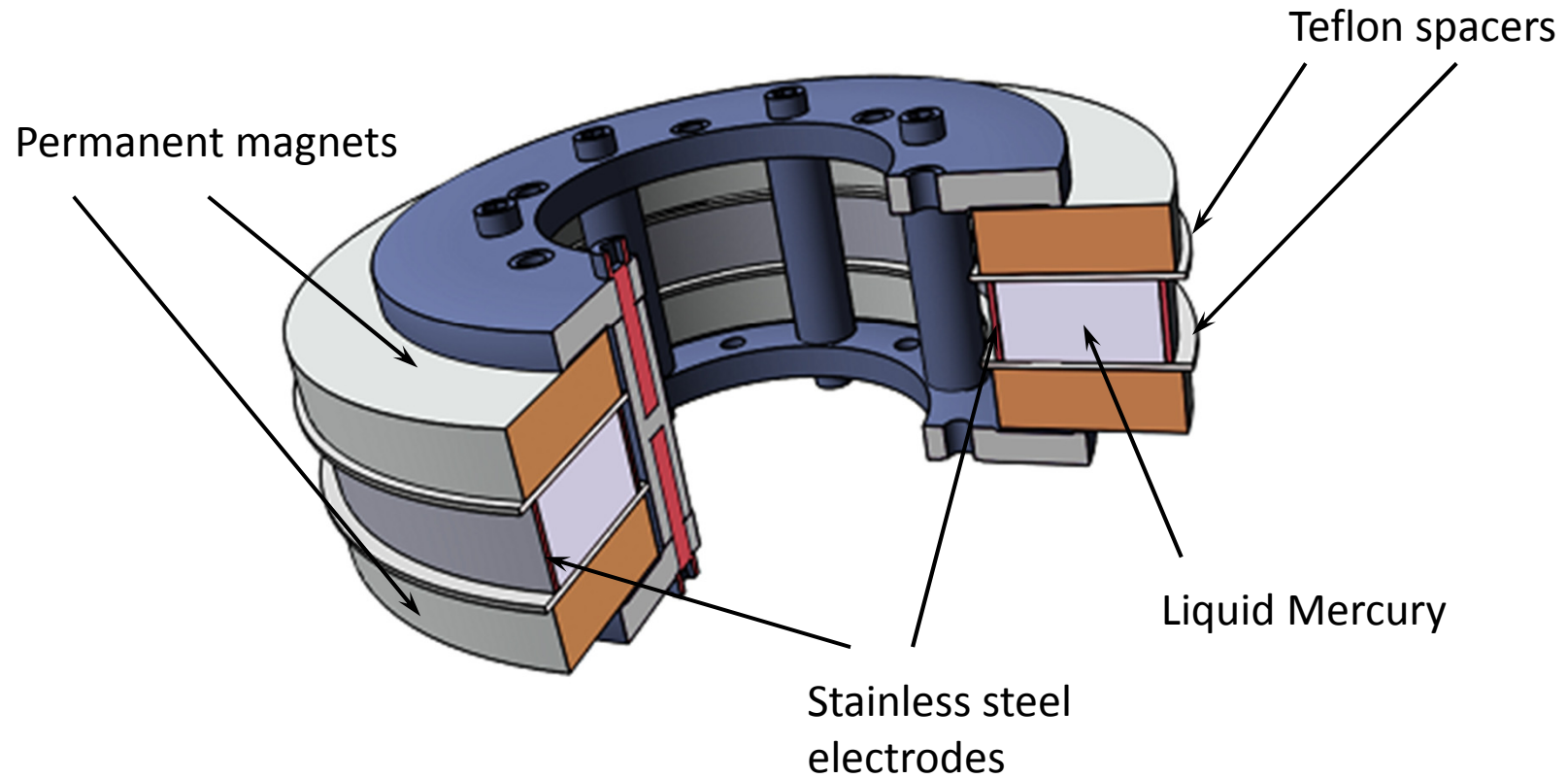
- Minimal number of moving parts
- Simple driving electronics
- High efficiency
- High reliability
- Inexpensive
- Hg is hard to work with (Health Hazard)
- Corrodes Aluminum
- Magnetic field containment
- Increased friction

# Our Implementation

- NdFeB Grade N42
- 13200 gauss
- 3" OD x 2" ID x 0.25"
- $\approx 0.3$  RPS/A



# Our Implementation





# Things to Improve on

- Material and Geometry optimization
- Accurate measurement of parameters

# Team



David Kvavadze



David Chkhaidze



Giorgi Tsomaia

The END